

Solution to 1. The given inequalities describing  $D$  imply that  $x, y, z \geq 0$ , and so  $x^2 \leq z^2$  implies  $x \leq z$ . Note also that  $x^2 \leq x$  implies that  $x \in [0, 1]$ . Therefore, we can give the equivalent description of  $D$ :

$$0 \leq x \leq 1, \quad x \leq z \leq \sqrt{x}, \quad x^2 \leq y \leq z^2.$$

We calculate:

$$\begin{aligned} \iiint_D \frac{20}{z-x} dx dy dz &= \int_0^1 dx \int_x^{\sqrt{x}} dz \int_{x^2}^{z^2} \frac{20}{z-x} dy = \\ &= \int_0^1 dx \int_x^{\sqrt{x}} \frac{20(z^2 - x^2)}{z-x} dz = \\ &= \int_0^1 dx \int_x^{\sqrt{x}} 20(z+x) dz = \\ &= \int_0^1 20(z^2/2 + xz) \Big|_{z=x}^{z=\sqrt{x}} dx = \\ &= \int_0^1 20(x/2 - x^2/2 + x^{3/2} - x^2) dx = \\ &= \int_0^1 10(x - 3x^2 + 2x^{3/2}) dx = \\ &= 10(1/2 - 1 + 4/5) = \\ &= 5 - 10 + 8 = 3. \end{aligned} \quad \square$$

Solution to 2. b):  $dx dy = 2ududv$ .

c): The domain  $B$  is the quarter-disk  $u^2 + v^2 \leq 1, 0 \leq u, 0 \leq v$ . Using the above change of coordinates, and then using polar coordinates  $u = r \cos(\theta), v = r \sin(\theta)$ , we calculate the integral:

$$\begin{aligned} \iint_A \sqrt{y-x} e^{(y+x^2-x)^2} dx dy &= \iint_B u e^{(u^2+v^2)^2} 2ududv = \\ &= \int_0^{\pi/2} 2 \cos^2(\theta) d\theta \int_0^1 r^3 e^{r^4} dr = \\ &= \int_0^{\pi/2} (\cos(2\theta) + 1) d\theta \int_0^1 r^3 e^{r^4} dr = \\ &= \left( \frac{\sin(2\theta)}{2} + \theta \right) \Big|_{\theta=0}^{\theta=\pi/2} \frac{e^{r^4}}{4} \Big|_{r=0}^{r=1} = \\ &= \frac{\pi(e-1)}{8}. \end{aligned} \quad \square$$

Solution to 3. b): Using spherical coordinates, we obtain the following parametrization for the surface  $\mathcal{S}$  of  $D$ :

$$\mathbf{r}(\phi, \theta) = (\sin(\phi)^2 \cos(\theta), \sin(\phi)^2 \sin(\theta), \sin(\phi) \cos(\phi)),$$

with  $0 \leq \phi \leq \pi$  and  $0 \leq \theta \leq 2\pi$ . Therefore,

$$d\mathbf{S} = \frac{\partial \mathbf{r}}{\partial \phi} \times \frac{\partial \mathbf{r}}{\partial \theta} d\phi d\theta = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 \sin(\phi) \cos(\phi) \cos(\theta) & 2 \sin(\phi) \cos(\phi) \sin(\theta) & \cos^2(\phi) - \sin^2(\phi) \\ -\sin^2(\phi) \sin(\theta) & \sin^2(\phi) \cos(\theta) & 0 \end{vmatrix} d\phi d\theta.$$

Note that this parameterization is such that the resulting normal vector field points out of  $\mathcal{S}$ . Namely, by calculating  $d\mathbf{S}$  at  $\mathbf{r}(\phi = \pi/2, \theta = 0) = (1, 0, 0)$  we obtain

$$d\mathbf{S} = \frac{\partial \mathbf{r}}{\partial \phi} \times \frac{\partial \mathbf{r}}{\partial \theta} d\phi d\theta = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{vmatrix} d\phi d\theta = \mathbf{i} d\phi d\theta,$$

and so the normal vector field is  $\mathbf{N}(1, 0, 0) = \mathbf{i}$ .

On  $\mathcal{S}$ , in the same parametrization, we have that

$$\mathbf{F} = \sin(\phi)^2 \cos(\theta) \mathbf{i} + \sin(\phi)^2 \sin(\theta) \mathbf{j} + \sin(\phi) \cos(\phi) \mathbf{j},$$

and so

$$\begin{aligned}
\mathbf{F} \cdot d\mathbf{S} &= \begin{vmatrix} \sin(\phi)^2 \cos(\theta) & \sin(\phi)^2 \sin(\theta) & \sin(\phi) \cos(\phi) \\ 2 \sin(\phi) \cos(\phi) \cos(\theta) & 2 \sin(\phi) \cos(\phi) \sin(\theta) & \cos^2(\phi) - \sin^2(\phi) \\ -\sin^2(\phi) \sin(\theta) & \sin^2(\phi) \cos(\theta) & 0 \end{vmatrix} d\phi d\theta = \\
&= \sin^3(\phi) \begin{vmatrix} \sin(\phi) \cos(\theta) & \sin(\phi) \sin(\theta) & \cos(\phi) \\ -\sin(\theta) & \cos(\theta) & 0 \\ 2 \sin(\phi) \cos(\phi) \cos(\theta) & 2 \sin(\phi) \cos(\phi) \sin(\theta) & \cos^2(\phi) - \sin^2(\phi) \end{vmatrix} d\phi d\theta = \\
&= \sin^3(\phi) \begin{vmatrix} \sin(\phi) \cos(\theta) & \sin(\phi) \sin(\theta) & \cos(\phi) \\ \sin(2\phi) \cos(\theta) & \sin(2\phi) \sin(\theta) & \cos(2\phi) \\ -\sin(\theta) & \cos(\theta) & 0 \end{vmatrix} d\phi d\theta = \\
&= -\sin^3(\phi) (\sin(\phi) \cos(2\phi) \cos^2(\theta) - \cos(\phi) \sin(2\phi) \sin^2(\theta) \\
&\quad + \sin(\phi) \cos(2\phi) \sin^2(\theta) - \cos(\phi) \sin(2\phi) \cos^2(\theta)) d\phi d\theta = \\
&= -\sin^3(\phi) (\sin(\phi) \cos(2\phi) - \cos(\phi) \sin(2\phi)) d\phi d\theta = \\
&= -\sin^3(\phi) (\sin(\phi) (\cos^2(\phi) - \sin^2(\phi)) - \cos(\phi) 2 \sin(\phi) \cos(\phi)) d\phi d\theta = \\
&= \sin^4(\phi) d\phi d\theta.
\end{aligned}$$

Thus, we can now calculate the flux of  $\mathbf{F}$  out of  $\mathcal{S}$ , and obtain:

$$\begin{aligned}
\iint_{\mathcal{S}} \mathbf{F} \cdot d\mathbf{S} &= \int_0^{2\pi} d\theta \int_0^\pi \sin^4(\phi) d\phi = \\
&= 2\pi \int_0^\pi \frac{1}{4} (1 - \cos(2\phi))^2 d\phi = \\
&= \frac{\pi}{2} \int_0^\pi (1 - 2\cos(2\phi) + \cos^2(2\phi)) d\phi = \\
&= \frac{\pi}{2} \int_0^\pi (1 - 2\cos(2\phi) + \frac{1}{2}(1 + \cos(4\phi))) d\phi = \\
&= \frac{\pi}{2} \left( \frac{3\pi}{2} - \sin(2\phi) \Big|_{\phi=0}^{\phi=\pi} + \frac{1}{8} \sin(4\phi) \Big|_{\phi=0}^{\phi=\pi} \right) = \\
&= \frac{3\pi^2}{4}.
\end{aligned}$$

We have that  $\operatorname{div}(\mathbf{F}) = 3$ . Using again spherical coordinates, we obtain:

$$\begin{aligned}
\iiint_D \operatorname{div}(\mathbf{F}) dx dy dz &= \int_0^{2\pi} d\theta \int_0^\pi d\phi \int_0^{\sin(\phi)} 3R^2 \sin(\phi) dR = \\
&= 2\pi \int_0^\pi \sin(\phi)^4 d\phi.
\end{aligned}$$

We obtain the same integral as above, therefore we obtain the relation in the divergence theorem:

$$\iint_{\mathcal{S}} \mathbf{F} \cdot d\mathbf{S} = \iiint_D \operatorname{div}(\mathbf{F}) dx dy dz. \quad \square$$

*Solution to 4. b):*  $\operatorname{curl}(\mathbf{F}) = 2x\mathbf{i} - 2z\mathbf{k}$ .

c): We use cylindrical coordinates to parameterize  $\mathcal{S}$ :

$$\mathbf{r}(\theta, z) = (\cos(\theta), \sin(\theta), z), \quad 0 \leq \theta \leq 2\pi, \quad \cos(\theta) \leq z \leq 2.$$

We have that

$$d\mathbf{S} = \frac{\partial \mathbf{r}}{\partial \theta} \times \frac{\partial \mathbf{r}}{\partial z} d\theta dz = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{vmatrix} d\theta dz = (\cos(\theta)\mathbf{i} + \sin(\theta)\mathbf{j}) d\theta dz.$$

Note that this with this choice, the normal vector field points out of  $\mathcal{S}$ .

In these coordinates, on  $\mathcal{S}$ , we have that

$$\operatorname{curl}(\mathbf{F}) = 2 \cos(\theta)\mathbf{i} - 2z\mathbf{k}.$$

Therefore

$$\begin{aligned}
 \iint_{\mathcal{S}} \mathbf{curl}(\mathbf{F}) \cdot d\mathbf{S} &= \int_0^{2\pi} d\theta \int_{\cos(\theta)}^2 2 \cos(\theta)^2 dz = \\
 &= 2 \int_0^{2\pi} (2 - \cos(\theta)) \cos(\theta)^2 d\theta = \\
 &= 2 \int_0^{2\pi} (1 + \cos(2\theta) - \cos(\theta)(1 - \sin(\theta)^2)) d\theta = \\
 &= 4\pi + 2 \left( \frac{1}{2} \sin(2\theta) - \sin(\theta) + \frac{1}{3} \sin(\theta)^3 \right) \Big|_{\theta=0}^{\theta=2\pi} = \\
 &= 4\pi.
 \end{aligned}$$

d): An oriented parameterization of  $\mathcal{C}_1$  is given by:

$$\mathbf{r}(\theta) = (\cos(\theta), -\sin(\theta), 1).$$

Therefore:

$$\oint_{\mathcal{C}_1} yz \, dx - xz \, dy + xy \, dz = \int_0^{2\pi} 2(\sin(\theta)^2 + \cos(\theta)^2) d\theta = 4\pi$$

e): By Stokes' Theorem:

$$\oint_{\mathcal{C}_2} \mathbf{F} \cdot d\mathbf{r} = \iint_{\mathcal{S}} \mathbf{curl}(\mathbf{F}) \cdot d\mathbf{S} - \oint_{\mathcal{C}_1} \mathbf{F} \cdot d\mathbf{r} = 0.$$

For verification, let us perform the calculation also directly. An oriented parameterization of  $\mathcal{C}_2$  is given by:

$$\mathbf{r}(\theta) = (\cos(\theta), \sin(\theta), \cos(\theta)).$$

Therefore:

$$\begin{aligned}
 \oint_{\mathcal{C}_2} yz \, dx - xz \, dy + xy \, dz &= - \int_0^{2\pi} (\cos(\theta) \sin(\theta)^2 + \cos(\theta)^3 + \cos(\theta) \sin^2(\theta)) d\theta = \\
 &= - \int_0^{2\pi} \cos(\theta)(1 + \sin^2(\theta)) d\theta = \\
 &= - \int_0^{2\pi} \sin(\theta) + \frac{1}{3} \sin^3(\theta) d\theta = 0.
 \end{aligned}$$

□